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Tetrahedral plot diagram:

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A geometrical solution for quaternary systems

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ABSTRACT

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The transformation from a tetrahedral four-component system to an XYZ-orthogonal

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coordinate axis system has been solved using the geometry of a tetrahedron. If a four

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component mixing ratio is described as t , l , r , and f (here, $t + l + r + f = 1$), the

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transforming equations can be written as, $x = (r + 1 - l) / 2$, $y = \frac{\sqrt{3}}{2}t + \frac{\sqrt{3}}{6}f$, and

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$z = \frac{\sqrt{6}}{3}f$. A tetrahedral plot diagram can be easily constructed using the algorithms

19 described in this paper. We present an implementation of these algorithms in a
20 custom-designed Microsoft Excel spreadsheet, including adjustable viewing angles for
21 the tetrahedral plot. This will be of general utility for petrological or mineralogical
22 studies of quaternary systems.

23 **Keywords:** Tetrahedral diagram, triangular diagram, quaternary systems, phase
24 diagram, three-dimension, trilinear coordinates, tetrahedron

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INTRODUCTION

27 Tetrahedral diagrams are commonly used in petrology and mineralogy, for example,
28 the Di-Fo-Ne-Qz diagram for basaltic rocks (Yoder and Tilley 1962), the An-Ab-Or-Qz
29 diagram for granitic rocks (Winkler 1979), and four-component metamorphic phase
30 diagrams (e.g., Thompson 1957; Spear 1993). The algorithm of transformation from a
31 tetrahedral four-component system to an XYZ-orthogonal coordinate system has been
32 addressed by several studies (e.g., Korzhinskii 1959; Mertie 1964; Arem 1971; Spear
33 1980; Armienti 1986; Maaløe et al. 2005; Armienti and Longo 2011). These authors
34 solved the transformation by vector and/or linear algebra using computer programs.
35 Computer applications for tetrahedral plots have also been presented by many authors
36 (e.g., Spear et al. 1982; Armienti 1986; Torres-Roldan et al. 2000; Ho et al. 2006;
37 Armienti and Longo 2011). Such applications are run on programming language
38 platforms such as FORTRAN, BASIC, and JAVA.

39 This paper describes a different solution of transformation from a tetrahedral to an
40 orthogonal coordinate system. It has been solved using the geometry of a tetrahedron,
41 and by combining three simple equations. By this method, a tetrahedral diagram can be
42 easily constructed, and without programming language; it can be designed with a spread
43 sheet application (e.g. Microsoft Excel).

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COORDINATE TRANSFORMATION

46 Ternary system to orthogonal coordinate system

47 Although the main theme of this paper concerns tetrahedral diagrams, it is first
48 necessary to explain a triangular diagram. The three components named here are Top
49 (T), Left (L), and Right (R), respectively. The point of interest is referred to as P (Fig. 1),
50 where the mixing ratios corresponding to P are expressed as t , l , and r (here, $t + l + r =$
51 1). The side length of the equilateral triangle is set to 1. The apex L conforms to the
52 origin of the X-Y orthogonal coordinate system. In this case, the coordinates (x, y) of
53 vertices T, L, and R are $(0.5, \frac{\sqrt{3}}{2})$, $(0, 0)$, and $(0, 1)$, respectively.

54 Since the x -coordinate of P is a center between L' and R' in Figure 1, then,

$$55 \quad x = (r + 1 - l) / 2 \quad (1a)$$

56 The y -coordinate of P can be calculated by the height ratio of the equilateral triangle,
57 namely;

$$58 \quad y = \frac{\sqrt{3}}{2} t \quad (1b)$$

59 The triangular diagram can be constructed using a frame line $(0.5, \frac{\sqrt{3}}{2}) - (0, 0) - (0, 1)$
60 and plot data (x, y) . According to equations 1a and 1b, if the $t + l + r = 1$ condition is
61 met, a negative component is also allowable. For example $(t, l, r) = (-0.1, 0.5, 0.6)$ is

62 also true. In this case, the point plots outside of the triangle. For example, in AFM
63 diagram (Thompson 1957), the composition of biotite, projected from muscovite, plots
64 outside the triangle.

65 An example of a triangular diagram constructed using Microsoft Excel can be
66 downloaded as a supplementary electronic file¹.

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68 **Quaternary system to orthogonal coordinate system**

69 The Z-axis extends from the origin of the X-Y orthogonal coordinate system (Fig. 2).

70 The four components are named here as Top (T), Left (L), Right (R), and Front (F),

71 respectively. Let TLR be a regular tetrahedron. The base triangle TLR is same as that

72 of the triangular diagram (Fig. 1). The point of interest is again named P, where the

73 mixing ratio of P is described as t , l , r , and f (here, $t + l + r + f = 1$). The side length of

74 the equilateral triangle is set to 1. The apex L conforms to the origin of the X-Y-Z

75 orthogonal coordinate system. The coordinates (x, y, z) of vertices T, L, R, and F are $(0.5,$

76 $\frac{\sqrt{3}}{2}, 0)$, $(0, 0, 0)$, $(1, 0, 0)$, $(0.5, \frac{\sqrt{3}}{6}, \frac{\sqrt{6}}{3})$, respectively, as dictated by the geometrical

77 feature of a regular tetrahedron (Fig. 2; see also Fig. A1 of appendix¹).

78 First, the relationship between the coordinate x and the components L and R is

79 illustrated. P lies on the line F'T', which is the intersection of the r and l isopleth

80 surfaces. Since the spatial figure T'L'R'F' is also a regular tetrahedron, the line F'T' is
81 parallel to the YZ-plane. Because the x coordinate of P is the same as T', x is given by
82 equation 1a,

$$83 \quad x = (r + 1 - l) / 2 \quad (2a)$$

84 The second consideration concerns the relation of y and T. The surface FLR, which is
85 the $t = 0$ plane, is not parallel with XZ-plane. Since the y -coordinate of apex F is $\frac{\sqrt{3}}{6}$, the
86 y -coordinate of P is, adding $\frac{\sqrt{3}}{6}f$ to equation 1b, gives -

$$87 \quad y = \frac{\sqrt{3}}{2}t + \frac{\sqrt{3}}{6}f \quad (2b)$$

88 The third consideration is the relationship between z and F. The $f = 0$ plane is same as
89 the XY-plane. Since the height of a regular tetrahedron is $\frac{\sqrt{6}}{3}$, then

$$90 \quad z = \frac{\sqrt{6}}{3}f \quad (2c)$$

91 In the XYZ orthogonal coordinate system, the tetrahedron frame can be constructed
92 using a line $(0.5, \frac{\sqrt{3}}{2}, 0) - (0, 0, 0) - (1, 0, 0) - (0.5, \frac{\sqrt{3}}{6}, \frac{\sqrt{6}}{3})$. The plot data (x, y, z) can be
93 calculated by equations 2a, 2b, and 2c (Fig. 2). According to these equations, the same
94 as described for the triangle diagram, if the $t + l + r + f = 1$ condition is met, a negative
95 component is also allowable. For example $(t, l, r, f) = (-0.1, 0.5, 0.6, 0)$ is also true. In
96 this case, the point plots outside of the tetrahedron.

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IMPLICATIONS

99 A tetrahedral diagram to enable visualization of four component systems can be
100 easily constructed using the algorithms described in this paper. After the transformation
101 from a tetrahedral to an orthogonal coordinate system, the tetrahedral diagram can be
102 rotated in 3D space using Euler angle equations. Both parallel and perspective
103 projections from 3D to 2D can be calculated. These projections, and tetrahedral
104 diagrams with user-specified viewing angles, can be drawn using a spreadsheet
105 application (e.g. Microsoft Excel), without the need for specialized programming
106 language. An example Microsoft Excel file is available as a supplemental electronic
107 file¹. Additional information concerning the derivation and rotation of tetrahedral
108 diagrams using the approach described above is presented in an appendix¹.

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150 natural and synthetic rock systems. *Journal of Petrology*, 3, 342-532.
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152 **Footnote to tetrahedral plot diagram**

153 ¹ Deposit item AM-XX-XXX, an Appendix and a Microsoft Excel file. Deposit items
154 are stored on the MSA web site and available via the American Mineralogist Table of
155 Contents. Locate the article in the table of contents at GSW
156 (ammin.geoscienceworld.org) or MSA (www.minsocam.org), and then click on the link
157 to the Deposit Item.

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159 **Figure Captions**

160 Figure 1. Geometrical relationships between the ternary system (triangular diagram) and
161 the XY-orthogonal coordinate axis system.

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163 Figure 2. Geometrical relationships between the quaternary system (tetrahedral
164 diagram) and the XYZ-orthogonal coordinate axis system.



